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**Analog Electronic Circuits**

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**Lesson #3**  
Outline

- Dynamic limitations of OpAmps
  - Open-loop response
  - Gain-Bandwidth product
- Drawing  $A_{OL}$ ,  $1/\beta$ ,  $\beta A_{OL}$
- Closed-loop response
  - The GBW trade-off
    - Resistive circuits
    - Frequency-dependent circuits
- Transient response
  - Slew-rate

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**Open-loop response**

LM324 (Texas Instruments, National)

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### Open-loop response

$A_{OL} = \frac{A}{1 + j\frac{f}{f_c}}$

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### Gain-Bandwidth Product - GBW

$A_{CL} = G \frac{A_{OL}}{1 + \beta A_{OL}}$

$\beta = 1, G = 1$

$A_{CL} = \frac{A_{OL}}{1 + A_{OL}}$

$GBW = A_{OL} f_c = f_{unity}$

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### Loop-Gain Nyquist Criterion

$$A_{CL} = G(s) \frac{A_{OL}(s)}{1 + \beta A_{OL}(s)}$$

- The system is unstable if the characteristic equation  $(1 + \beta A_{OL}(s))$  has roots in the right half of the complex plane
- Nyquist criterion is a test for location of  $(1 + \beta A_{OL}(s))$  roots
- Nyquist criterion can be viewed on the frequency domain (Bode)

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### Loop-gain on the frequency domain

In negative feedback systems  $\phi = 180^\circ (-180^\circ)$   
 At  $f \rightarrow 0$

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### Bode plot Phase margin

$\phi_m = \phi_{|\beta A|=1} - (-180^\circ) = \phi_{|\beta A|=1} + 180^\circ$

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### Graphical representation of $\beta A_{OL}$ conventional method

- Tedious – need to re-plot BA
- Analysis (not design) oriented
- Requires iterations

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### Graphical Representation of $\beta A_{OL}$

$$20\log A - 20\log \frac{1}{B} = 20\log(BA)$$

$$20\log A = 20\log \frac{1}{B} \Rightarrow B \cdot A = 1$$

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### Closed-loop response Non-inverting Amp

$$G = 1$$

$$\frac{1}{\beta} = \frac{R_1 + R_2}{R_2}$$

$$GBW = A_0 f_c = f_{unity}$$

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### Closed-loop response Inverting Amp

$$G = \frac{R_2}{R_1 + R_2}$$

$$\frac{1}{\beta} = \frac{R_1 + R_2}{R_2}$$

$$GBW = A_0 f_c = f_{unity}$$

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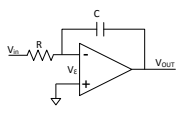
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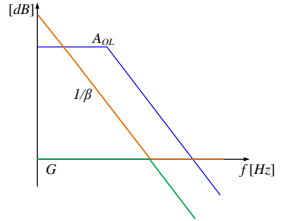
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### Closed-loop response Integrator



$$G = \frac{1}{sCR + 1}$$

$$\frac{1}{\beta} = \frac{sCR + 1}{sCR}$$

$$GBW = A_0 f_c = f_{unity}$$



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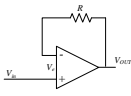
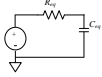
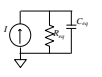
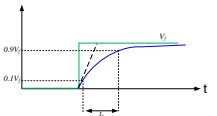
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### Transient response Rise-time (ideal)


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